

SPECIFICATION

Product Name: Laser Particle Sensor Module

Item No.: PM2105L

Version: V0.3

Date: December 26th, 2022

Revision

| No. | Version | Content | Date |
|-----|---------|-------------------------------|------------|
| 1 | V0.1 | The first edition | 2019.5.27 |
| 2 | V0.2 | Update MTTF and UART protocol | 2022.1.26 |
| 3 | V0.3 | Update IIC protocol | 2022.12.26 |
| | | | |

Laser Particle Sensor Module



PM2105L



Applications

- Air purifier
- Air quality monitor
- Air conditioner
- Ventilation system
- Consumer electronic products
- Environmental monitoring

Description

PM2105L is a laser particle sensor module for indoor use based on laser scattering technology. This sensor can measure particle concentration size between 0.3µm~10µm exactly and output particle mass concentration PM1.0, PM2.5, PM10 in µg/m³ directly via mathematical algorithm and scientific calibration.

Features

- The smallest size of available measurement: 0.3µm
- Real-time output PM1.0, PM2.5, PM10 in µg/m³ available
- High accuracy, high sensitive and quick response (≤4s)
- Signal output optional: UART, I²C, PWM
- RoHS and Reach compliant
- Air inlet and outlet on different side

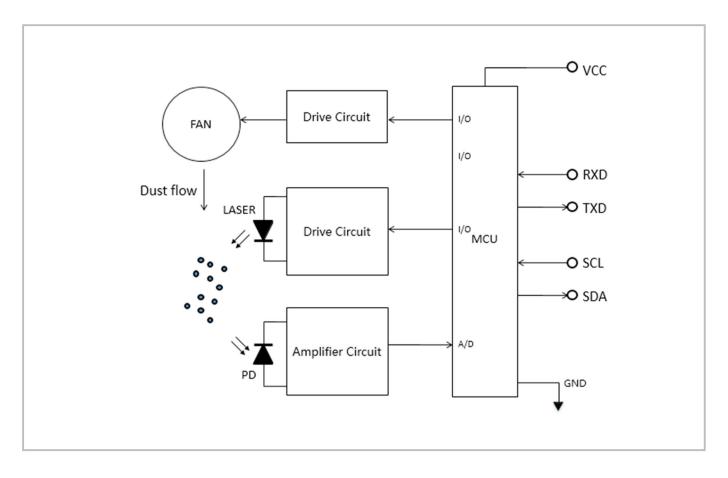
Working Principle

Sampling by the internal pressure which occurs by fan, when sampling particles pass through light beam (laser), there will be light scattering phenomenon. Scattered light will be converted into electrical signal (pulse) via photoelectric transformer. The bigger particles will obtain stronger pulse signal (peak value). Through peak value and pulse value quantity concentration of particles in each size can be calculated. Thus, real-time measured data is obtained through measuring quantity and strength of scattered light.

Specifications

| Laser Particle Sensor Specification | on | | |
|-----------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------|--|--|
| Operating principle | Laser scattering | | |
| Measured particle range | 0.3μm ~ 10μm | | |
| Measurement range | 0~5000µg/m³ | | |
| Resolution | 1µg/m³ | | |
| Working condition | -10°C ~ 60°C, 0-95%RH (non-condensing) | | |
| Storage condition | -40°C ~ 80°C, 0-95%RH (non-condensing) | | |
| Measurement accuracy for PM1.0&PM2.5 | 0 ~100μg/m³, ±10μg/m³ >100μg/m³, ±10% of reading Condition: 25±2℃, 50±10%RH, Reference instrument: GRIMM Dust source: Cigarette+A1 | | |
| Measurement accuracy for PM10 | 0 ~100μg/m³, ±30μg/m³ 101 ~1000μg/m³, ±30% of reading Condition: 25±2°C, 50±10%RH, Reference instrument: GRIMM Dust source: Cigarette+A1 | | |
| Response time | 1sec | | |
| Time to first reliable reading | ≤ 4 seconds | | |
| Power supply | DC 5V±0.1V Ripple wave<50 mV | | |
| Working current | <53 mA | | |
| Standby current | <5 mA | | |
| Dimensions | 42×35×23.7 mm | | |
| Digital output 1 (default) | UART_TTL (3.3V, compatible with 5V) I ² C (3.3V, compatible with 5V) | | |
| Digital output 2 | PWM (customized) | | |
| Output method | Default by active output after powering on, sampling time interval should be over 1,000 ms | | |
| MTTF | 128,000 hrs (continuous operation) | | |

Internal Architecture Description

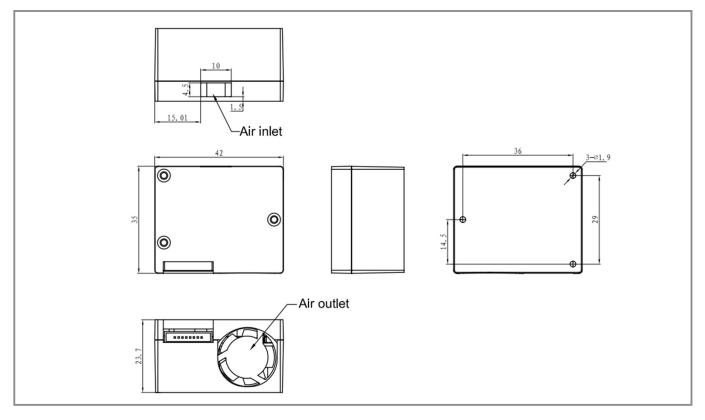


When the fan works, it will generate airflow. When the particles in the sampled gas pass through the beam of the light source (laser), a light scattering phenomenon occurs, and the scattered light is converted into an electrical signal (ie, a pulse) by the photoelectric transformer. The larger the particle size, the larger the amplitude of the pulse signal outputs.

The number of particles of different sizes is calculated by comparing the peak value with the predetermined threshold value, and the mass concentration value is obtained by a professional algorithm. By testing the intensity of the scattered light, real-time test data is obtained.

Dimensions and Connector

1. Dimensions (Unit mm, tolerance ±0.2 mm)



2. I/O Connector Pinout

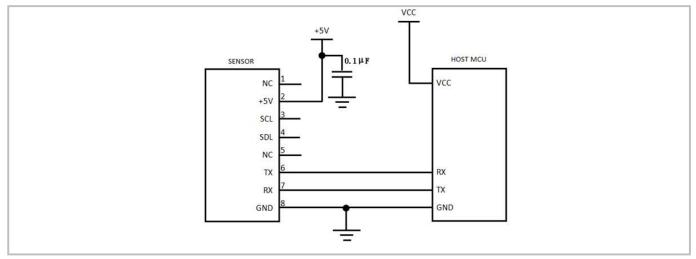


The interface connector is located at the side of the sensor.

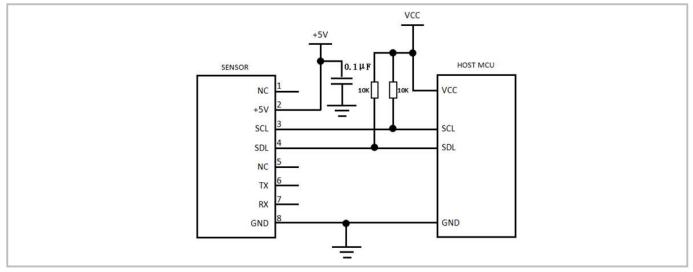
Corresponding female plug model can be SM08B-GHS-TB from JST. The pitch distance is 1.25mm. The connection cable with female connector at both ends can also be customized.

Typical Application Circuit

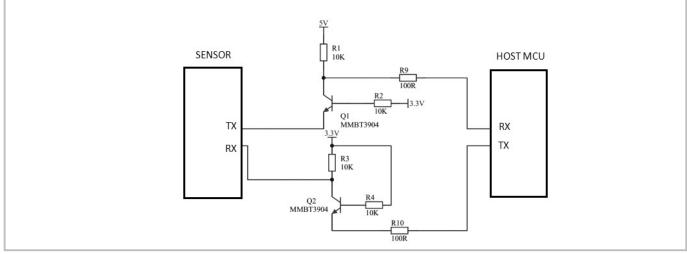
Case 1. UART Application



Case 2. I²C Application

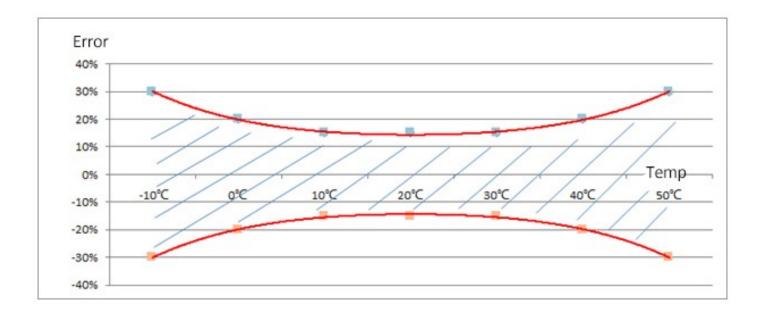


Case 3: 5V-3.3V Level Shift, RX, TX Level Shift



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Temperature Influence Curve



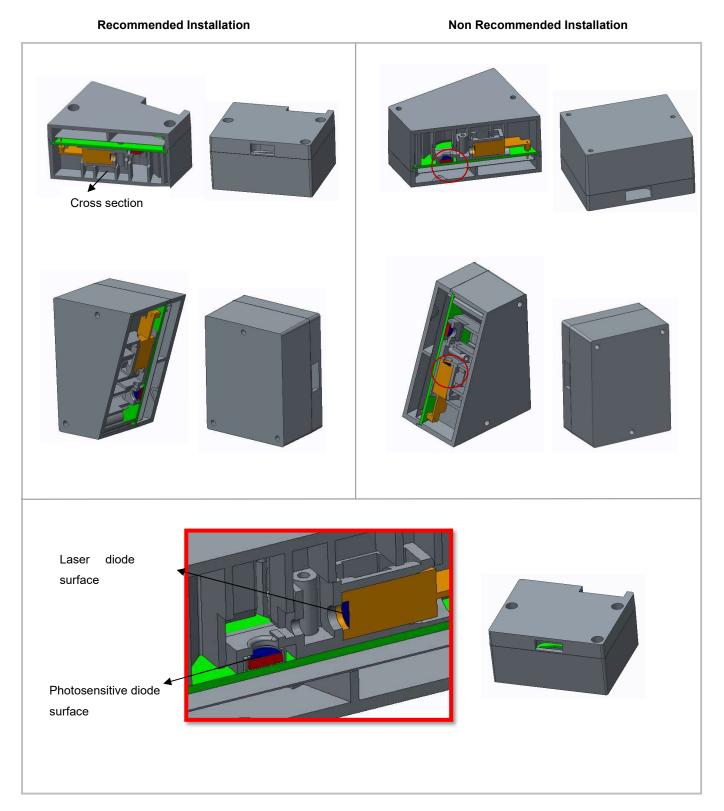
Particle measured error: under 25 ± 2 °C, 0~1,000µg/m³, consistency and accuracy of PM1.0/PM2.5 is either $\pm 15\%$ reading or $\pm 15\mu$ g/m³, whichever is larger.

Temperature influence coefficient: 0.5%/°C ~ 1%/°C or 0.5μ g/m³/°C ~ 1μ g/m³/°C, whichever is larger.

Product Installation

•When install PM2105L sensor module in your system or equipment, please make sure that the air inlet and air outlet are unobstructed. And there is no huge airflow face to air inlet and air outlet.

In order to avoid dust deposition on the surface of sensitive component (laser diode and photosensitive diode), which may affect the measurement accuracy of the sensor, the appropriate installation ways are recommended as below.



User Attention

•For purification products, sensor cannot be installed in the purifying air duct. If it's not possible, it's necessary to design a separate structure for sensor installation to isolate the sensor from air purifier duct.

•For purifier and detector device, sensor should be installed above 20cm higher than floor to avoid contamination of large dust particles or even flocs near the ground entering the sensor, which will influence the measurement.

•Sensor should be prohibited from using for outdoor inspection equipment. Dust storms, rain, snow, and willow flocs can have a significant impact on unprotected sensors.

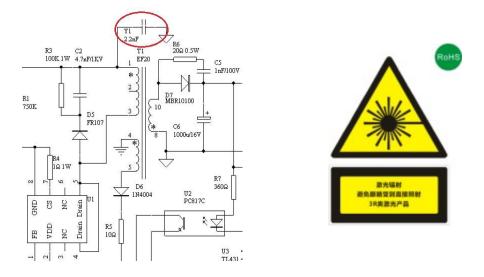
•It is for household electronics products. For application of medical, mining, disaster preparedness, which needs high security and high dependence, this sensor is not suitable.

-Avoid using the sensor under the condition with strong magnetic, such as situation close to stereo speaker, microwave oven, induction cooking.

•There is no high pressure transient protection circuit of the sensor. The power supply of the sensor should be stable and low noise. Please refer to the working voltage in specification table.

•The sensor needs 5V power supply because the fan needs a 5V power to drive. But all other data communication and control pins require 3.3V as a high level. Therefore, the main board MCU communication with the sensor should be the 3.3V communication level. If the main board MCU is 5V communication level, then it need to connect 5V to 3.3V level conversion chips or circuits outside the communication port (RX, TX) and control port (RET, RESET).

•If isolated switch power supply is adopted to obtain DC power, please control the capacitance between the DC ground and the AC ground below 2.2nF and withstand voltage reaches to 3KV.



•This product is defined as 3R laser product according to 《GB7247.1-2012 laser product safety》 with laser radiation inside. Please avoid direct exposure to your eyes. Warning sign is as shown above.

UART Communication Protocol

1. General Statement

1) The data in this protocol is all hexadecimal data. For example, "46" for decimal [70].

2) [xx] is for single-byte data (unsigned, 0-255); for double data, high byte is in front of low byte.

3) Baud rate: 9600; Data Bits: 8; Stop Bits: 1; Parity: No

2. Format of Serial Communication Protocol

| Sending format of s | software: |
|---------------------|-----------|
|---------------------|-----------|

| Start Symbol | Length | Command | Data 1 | Data n. | Check Sum |
|--------------|--------|---------|--------|-----------|-----------|
| HEAD | LEN | CMD | DATA1 | DATAn | CS |
| 11H | XXH | XXH | XXH | XXH | ХХН |

Detail description on protocol format:

| Protocol Format | Description | |
|--------------------------------------------------------------------------------------|------------------------------------------------------------|--|
| Start symbol Sending by software is fixed as [11H], module respond is fixed as [16H] | | |
| Length | Length of frame bytes= data length +1 (including CMD+DATA) | |
| Command | Command | |
| Data | Data of writing or reading, length is not fixed | |
| Check sum | Cumulative sum of data = 256- (HEAD+LEN+CMD+DATA)%256 | |

3.Command Table of Serial Protocol

| Item No. | Function Description | Command |
|----------|-------------------------------------------------|---------|
| 1 | Read particle measurement result | 0x0B |
| 2 | Open/close particle measurement | 0x0C |
| 3 | Set up and read particle calibrated coefficient | 0x07 |
| 4 | Read software version number | 0x1E |
| 5 | Read serial number | 0x1F |

4. Detail Description of RS232 Protocol

4.1 Read Particle Measurement Result Send: 11 02 0B 07 DB Response: 16 35 0B DF1- DF52 [CS] Function: Read concentration of particle

Note: Read particle concentration (ug/m3)

PM1.0 GRIMM mass concentration = DF1*256^3 + DF2*256^2 + DF3*256^1 + DF4 PM2.5 GRIMM mass concentration = DF5*256^3 + DF6*256^2 + DF7*256^1 + DF8 PM10 GRIMM mass concentration = DF9*256^3 + DF10*256^2 + DF11*256^1 + DF12

DF49: Alarm of sensor module working condition:

| Bit | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
|------------|-------|-------|-------|-------|----------------|-----------------|-----------------|-----------------|
| Alarm | | | | | 1: low working | 1: high working | 1: Fan at low | 1: Fan at high |
| definition | | | | | temperature | temperature | revolving speed | revolving speed |

DF13-DF48, DF50-DF52: Reserved

Note: Part of reserved bytes is used for Cubic internal testing. The data changeable of reserved bit is nothing related to Function.

4.2 Open/Close Particle Measurement
Send: 11 03 0C DF1 1E CS
Response: 16 02 0C DF1 CS
Function: Open/ close particle measurement

Note:

1. When sensor is power-on, it starts continuous measuring.

2. When sending command, DF1=02 means opening measurement, DF1=01 means closing measurement;

3. When receiving response, DF1=02 means measuring opened, DF1=01 means measuring closed;

4. When the sensor receives the command of opening measurement, it will be in default continuous testing mode. Pls check as below:

Example:

Send: 11 03 0C 02 1E C0// Open particle measurementResponse: 16 02 0C 02 DA//module is under particle measurement open status

Send: 11 03 0C 01 1E C1// Close particle measurementResponse: 16 02 0C 01 DB// module is under particle measurement closed status

4.3 Set up and Read Particle Calibrated Coefficient

Send: 11 02 07 DF1 [CS] // Set up particle calibrated coefficient
Send: 11 01 07 E7 // Read particle calibrated coefficient
Response: 16 02 06 DF1 [CS]
Function: Read/set up particle calibrated coefficient

Note:

1. Range 70~150 Corresponding coefficient: 0.7~1.5

Description:

1. When there is difference between standard device, calibrated coefficient can be set to correct the final value.

2. When calibrated coefficient is set, the value of PM1.0, PM2.5 and PM10 will be all corrected by this coefficient.

4.4 Read Software Version Number

Send: 11 01 1E D0 Response: 16 0E 1E DF1~DF13 [CS] www.en.gassensor.com.cn Function: Read software version

Note: Software version= "DF1~DF13" Should change the HEX code to ASCII code.

Example: HEX code: 16 0E 1E 50 4D 20 56 31 2E 32 36 2E 35 2E 32 38 E9 ASCII code: PM V1.26.5.28

4.5 Read Serial Number

Send: 11 01 1F CF Response: 16 0B 1F DF1 DF2 DF3 DF4 DF5 DF6 DF7 DF8 DF9 DF10 CS Function: Read serial number

Note:

Serial number =(DF1*256+DF2), (DF3*256+DF4), (DF5*256+DF6), (DF7*256+DF8), (DF9*256+DF10)

Example:

Response: 16 0B 1F 00 00 00 7E 09 07 07 0E 0D 72 9E Serial number: 0000 0126 2311 1806 3442

I²C Communication Protocol

1. Brief Introduction

a. This is an I²C protocol for PM2105L. The sensor module is lower computer, which is not able to initiate communication automatically. Communication is initiated via main controlled board, which reads data and Sends control commands.

b. Communication clock frequency <=100Khz.

2. Communication Common Description

START: start signal, send by main controlled board;

STOP: stop signal, send by main controlled board;

ACK: acknowledge signal, send by the sensor module if in bold; otherwise, send by main controlled board; NACK: non-acknowledge signal, send by the sensor module if in bold; otherwise, send by main controlled board; Px: receive and send data; send by the sensor module if in bold; otherwise, send by main controlled board.

3. Protocol Detailed Description

3.1 Send Command Data

Send by main controlled board:

START+WRITE+ACK+P1+ACK+P2+ACK...... +P7+ACK+STOP

| Data | Byte Content | Description | | |
|-------------------|---------------------------------------|----------------------------------------------------------------------------------------------------------------------|--|--|
| Device address | Sensor address and read/write command | This byte is 0xA0 when write data | | |
| P1 | 0x16 | Frame header | | |
| P2 | Frame length | Number of bytes, not including length of device address (From P1 to P7, 7 bytes in total) | | |
| P3 | Data 1 | Control command of the sensor as: Close measurement: 1 Open measurement: 2 Set up calibration coefficient:6 | | |
| P4 | Data 2, high byte | Calibration coefficient: (Range: 70~150, Corresponding: 0.7~1.5) | | |
| P5 | Data 2, low byte | | | |
| P6 | Data 3 | Reserved | | |
| P7 | Data check code | Check code= (P1^P2^^P6) | | |

3.2 Read Command Data

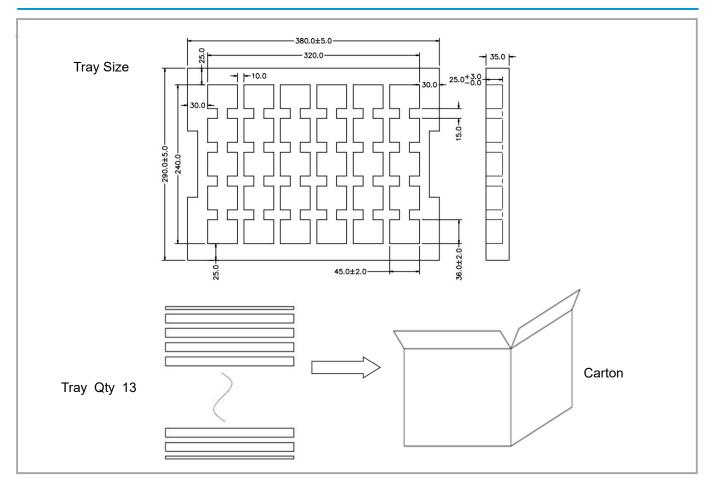
Send by main controlled board:

START+READ+ACK+P1+ACK+P2+ACK+.....+P32+NACK+STOP

| Data | Byte Content | Description | | |
|---------|--------------------|--------------------------------------------------------------------------------------------|--|--|
| Device | Sensor address and | This hat is 0404 when read date | | |
| address | read/write command | This byte is 0xA1 when read data | | |
| P1 | 0x16 | Frame header | | |
| P2 | Frame length | Number of byte, not including length of device address (from P1 to P32, 32 bytes in total) | | |
| P3 | Sensor status | Close: 1 | | |

| | | Alarm: 7 | | | |
|-----|--------------------|--------------------------------------------------------------------|--|--|--|
| | | Measuring: 2 | | | |
| | | Other data is invalid. | | | |
| P4 | Data 1, high byte | Deserved | | | |
| P5 | Data 1, low byte | Reserved | | | |
| P6 | Data 2, high byte | Orlikesting and Weingth (Dennes 70, 450, Orman and ing 0, 7, 4, 5) | | | |
| P7 | Data 2, low byte | Calibration coefficient: (Range: 70~150, Corresponding: 0.7~1.5) | | | |
| P8 | Data 3, high byte | DN/1 0 concentration with we/re3 CDIN/N | | | |
| P9 | Data 3, low byte | PM1.0 concentration , unit: μg/m³, GRIMM | | | |
| P10 | Data 4, high byte | DM2.5 concentration write wa/m ³ CDIMM | | | |
| P11 | Data 4, low byte | PM2.5 concentration , unit: μg/m³, GRIMM | | | |
| P12 | Data 5, high byte | PM10 concentration , unit: µg/m³, GRIMM | | | |
| P13 | Data 5, low byte | | | | |
| P14 | Data 6, high byte | | | | |
| P15 | Data 6, low byte | | | | |
| P16 | Data 7, high byte | | | | |
| P17 | Data 7, low byte | | | | |
| P18 | Data 8, high byte | | | | |
| P19 | Data 8, low byte | | | | |
| P20 | Data 9, high byte | | | | |
| P21 | Data 9, low byte | | | | |
| P22 | Data 10, high byte | Decem/ed | | | |
| P23 | Data 10, low byte | Reserved | | | |
| P24 | Data 11, high byte | | | | |
| P25 | Data 11, low byte | | | | |
| P26 | Data 12, high byte | | | | |
| P27 | Data 12, low byte | | | | |
| P28 | Data 13, high byte | | | | |
| P29 | Data 13, low byte | | | | |
| P30 | Data 14, high byte | | | | |
| P31 | Data 14, low byte | | | | |
| P32 | Data check code | Check code = (P1^P2^^P31) | | | |

Packing Information



| Sensor per Tray Tray Qty | | Sensor per Carton | Carton Dimensions | Packing Material | |
|--------------------------|-----------|-------------------|-------------------|------------------------|--|
| 30 pcs | 13 layers | 390 pcs | 395*310*480 mm | Red pearl cotton (ESD) | |

After-Sales Services and Consultancy

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